				Bia	lystok U	Iniversit	ty of Te	chnology	
				Fa	culty of	Electri	cal Eng	ineering	
Field of study			Indust	ry Digit	ization		and programme	full-time Bachelor's degree	
Specjalization / diploma path			com	mon su	bject		Study profile	general academic	
		F	undam	ontale o	fcontre		Course code	CP1S03001	
		1	unuann			,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		Course type	obligatory
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities	30		30		30			No. of ECTS credits	7
Entry requirements					Mathe	ematics	1, Math	ematics 2,	Physics
Course objectives	Acquair model c criteria its para stability	Acquainting with the theory of automation and the structure of automation systems. Acquiring the ability to nodel components of automatic control systems and determine their characteristics. Acquainting with the criteria for testing the stability of automatic control systems, the role of the controller and principles of tuning ts parameters, evaluation of the control system operation. Introduction of the concept of nonlinearity and stability analysis of nonlinear control systems.							
Course content	Lecture: Introduce describ accurace control. and det of state mathen diagran control Laboratory Determ (P, PI, I speed, Specialistic Calcula objects Stability	ction to a ing obje cy and d Stability ermination variable natical d ns and the laws, pro- classes: ining cha classes: ining cha classes: classes: ining cha classes: ining cha classes: ining cha classes: classes: classes: ining cha classes: c	automati cts of au ynamic j y of nonl on of op es. Open escriptioneir trans operties aracteris uning of vel, flow transfer ation of s control s	c contro itomatic performa inear au erator tran on, exam sformatic and dyn stics of c f PID co , temper function substitut ystem. I ear syst	I: basic control. ance of c tomatic ansfer fun- sfer fun- sfer fun- ples. St ons. Cor namic ch ontrol of ntroller p rature. of control e transfe Determin ems. Sir	concepts Stability control s unction and atic, dyn atic, dyn atic, dyn trol objec aracteris	s, signa of linea ystems. Systems Mather d matrix amic ar ects: typ stics, se dentifica ers. Tes ts. Anal on (trans static a of conti	Is, automat ar control sy Performan . Linearizat natical desc equations nd frequence es, propert election met tion of the aut stion of the aut ytical calcu sformations ccuracy an rol system i	ic control system (ACS). Equations /stems. Stability test criteria. Static ce indicators. Nonlinearities in automatic ion of nonlinear systems. The concept ription of dynamical systems in the space of state. Basic linear objects: types, cy characteristics of control objects. Block ies, examples, identification. Controllers: thods.
Teaching methods	Informa demons	itive-prol stration,	olem lec instructi	ture; Lal on and c	boratory discussio	classes on;	; Classe	es in compu	uter methods and techniques with
· .	Lec	ture: ex	am						

Assessment method	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes									
	Specialistic workshop: evaluation of reports, individual progress, dis	scussion and	activity at w	vorkshop						
Symbol of learning outcome	Learning outcomes	Reference to the	learning outcom study	es for the field of						
	Knowledge: the graduate knows and understands									
LO1	components and operation of the automatic control system	CP1 W03								
LO2	methods of testing performance and stability of an automatic control system	nce and stability of an automatic control CP1_W01								
LO3	procedure for control parameters tuning in automatic control systems	CP1_W04								
	Skills: the graduate is able to									
LO4	design a simple control system and tune the parameters of the PID controller	CP1_U07								
LO5	use known methods and mathematical models to analyze and evaluate the operation of a simple automatic control system									
LO6	apply principles of occupational health and safety in laboratory classes	CP1_U13								
Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition	during which the assessed	ne outcome is						
L01	Lecture: exam;	W								
LO2	Lecture: exam; Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;									
LO3	Lecture: exam; Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	W	L							
LO4	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes; Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		L	Ps						
LO5	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes; Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		L	Ps						
LO6	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	L								
	Student workload (in hours)		No. of hours							
	Lecture attendance		30							
	Laboratory classes attendance		30							
	Workshop attendance		30							
	Preparation for the lecture exam; participation in the exam		23							
Calculation	Preparation for laboratory classes		17							
	Preparation for laboratory classes completion		6							
	Preparation for specialistic workshop		26							

	Preparation for workshop completion	8								
	Participation in teacher-student sessions related to the module subject	5								
	TOTAL	175								
	Quantitative indicators	Hours ECTS								
	Student workload - activities that require direct teacher participation	97	3,9							
	Student workload - practical activities	122	4,9							
 Kowal J., Podstawy automatyki. T. 1, Uczelniane Wydawnictwa Naukowo-Dydaktyczne AGH, I 2006. Kowal J., Podstawy automatyki. T. 2, Uczelniane Wydawnictwa Naukowo-Dydaktyczne AGH, I 										
Basic references	2007. 3. Siemieniako F., Gosiewski Z., Automatyka. Tom. 1, Modelowanie i analiza układów. Wydawnictwo Reliteztralni Bielestadziej Bielestadu 2000									
	4. Prajs Z., Podstawy automatyki w zadaniach: układy liniowe ciągłe. Oficyna Wydawnicza Politechniki Białostockiej, Białystok, 2010.									
	5. Luft M., Łukasik Z., Podstawy teorii sterowania. Politechnika Radom	ska, Radom 2012.								
	1. Gosiewski Z., Siemieniako F., Automatyka. Tom. 2, Synteza układóv Białostockiej, Białystok, 2007.	v. Wydawnictwo Politechr	niki							
Supplementary	2. Mazurek J., Vogt H., Żydanowicz W., Podstawy automatyki. Oficyna Wydawnicza Politechniki Warszawskiej, Warszawa, 2002.									
references	 Dębowski A., Automatyka: podstawy teorii. WNT, Warszawa 2016. Łysakowska B., Mzyk G., Komputerowa symulacja układów automatycznej regulacji w środowisku Matlab/Simulink, Oficyna Wyd. PW, Wrocław 2005. 									
	5. Ogata K., Modern control engineering. Prentice-Hall, 2010.									
Organisational unit conducting the course	Department of Automatic Control and Robotics	Date of issuing the programme								
Author of the programme	dr hab. inż. Łukasz Sajewski, prof. PB 2022-06-07									

				Bia	lystok l	Iniversi	ty of Te	chnology	
				Fa	culty of	fElectri	cal Eng	ineering	
Field of study			Indust	ry Digit	ization			and programme	full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile	general academic
-		F	•					Course code	CP1S03002
Course name	Fundamentals of robotics						Course type	obligatory	
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities	30	30	30					No. of ECTS credits	7
Entry requirements					Math	ematics	1, Mathe	ematics 2, I	Physics
Course objectives	Acquain and the	nting with	h basic l onents.	knowled	ge relate	∋d to rob	otics as	well as wit	th the structure and application of robots
Course content	Classifi and act Working Jacobia tools us Classes: Modelir Laboratory	Lecture: Classification of robots, kinematic structures, concepts of the theory of machines and mechanisms. Sensors and actors used in robots. Description of coordinate system transformations. Modeling of kinematic chains. Working and configuration space. Simple and inverse kinematics task. Denavit-Hartenberg (D-H) notation, Jacobians and singularities of manipulators. Interpolation methods. Introduction to information technology tools used in robotics. Classes: Modeling the kinematics of a serial robot. Laboratory classes: Modeling the kinematics of a serial robot in a simulation environment. Programming of real industrial robots.							
Teaching methods	Informa	itive-proł	blem lec	ture; Cla	asses; L	aborator	y classe)S;	
Assessment method	Lec Cla Lat	ture: exa sses: tw oratory:	am ^r o tests evaluat	ion of in	troducto	ry tests,	reports,	discussior	n and activity during the classes
Symbol of learning outcome				Lear	rning outcor	mes			Reference to the learning outcomes for the field of study
			Knowledg	ge: the gra	duate knov	vs and und	erstands		
LO1	basic ro	obotics to	erms						CP1 W01 CP1 W02 CP1 W03
LO2	method	is of solv	/ing com	putatior	al tasks	related	to robot	ics	CP1 W01 CP1 W02
LO3	method	is and to	ols for m	obot pro	grammir	ng			CP1 W07
				Skills: the	graduate	is able to			
LO4	develop inverse) a mode tasks of	el of robo f manipu	ot kinem Jator kir	atics, fin nematics	ıd solutic	ons for s	imple and	CP1_U02 CP1_U06 CP1_U07 CP1_U09

LO5	operate and program the selected industrial manipulator		U02	CP1 U03	CP1 U0		
LO6	apply principles of occupational health and safety in laboratory classes	CP1	_U13				
Symbol of learning outcome	Methods of assessing the learning outcomes	Туре	of tuitio	n during which t assessed	he outcome is		
LO1	Lecture: exam; Classes: two tests;	W	С				
LO2	Lecture: exam; Classes: two tests;	W	С				
LO3	Lecture: exam; Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	W		L			
LO4	Classes: two tests; Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;		С	L			
LO5	Classes: two tests; Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;		С	L			
LO6	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	L					
	Student workload (in hours)			No. of hours			
	Lecture attendance			30			
	Classes attendance	30					
	Laboratory classes attendance		30				
	Preparation for the lecture exam; participation in the exam			28			
Osta tatian	Preparation for classes			18			
Calculation	Preparation for classes completion			6			
	Preparation for laboratory classes		22				
	Preparation for laboratory classes completion		6				
	Participation in teacher-student sessions related to the module subject	5					
	TOTAL	. 175					
	Quantitative indicators		Но	urs	ECTS		
	Student workload - activities that require direct teacher participation		9	7	3,9		
	Student workload - practical activities		1	17	4,7		
Basic references	 Honczarenko J., Roboty przemysłowe: budowa i zastosowanie. WNT Zdanowicz R., Podstawy robotyki. WPŚ, Gliwice, 2011. Szkodny T., Zbiór zadań z podstaw robotyki. WPŚ, Gliwice, 2013. Craig J. J., Wprowadzenie do robotyki. Mechanika i sterowanie. WNT Spong M. W., Vidyasagar M., Dynamika i sterowanie robotów, WNT, Koztowski K., Dutkiewicz P., Wróblewski W., Medalewszie i sterowanie 	T, War T, War Wars:	szawa szawa szawa, zawa,	, 2010. 1, 2003. 1997.	70110 2000		
Supplementary references	 Kozłowski K., Dutkiewicz P., Wróblewski W., Modelowanie i sterowa Buratowski T., Postawy robotyki. Uczelniane Wydawnictwa Naukowo Wittbrodt E., Adamiec-Wójcik I., Wojciech S. Dynamics of flexible mu method. Springer Science & Business Media, 2007. Adamiec-Wójcik I., Modelling dynamics of multibody systems using I Wydawnictwo ATH, 2003. Morecki A., Knapczyk J., Podstawy robotyki, WNT, Warszawa 1999. 	nie roł p-Tech ultibod homog	potów. Iniczne ly syste Jenous	PWN, Wars: AGH, Krake ems: rigid fin transformat	zawa, 2003 ów 2006. ite elemen ions.		

Organisational unit conducting the course	Department of Automatic Control and Robotics	Date of issuing the programme
Author of the programme	dr inż. Adam Wolniakowski	2022-06-07

				Bia	lystok U	Iniversit	ty of Te	chnology	
				Fa	culty of	Electri	cal Eng	ineering	
Field of study			Industi	ry Digit	ization			and programme	full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile	general academic
		(`ompute	ar aidad	design	1	Course code	CP1S03003	
			,ompute		uesigii	1		Course type	obligatory
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities	15				30			No. of ECTS credits	3
Entry requirements				Technic	cal draw	ing, Elec	ctronic c	omponents	s and subsystems
Course objectives	Acquair creating Electric and trar	Acquainting with selected applications used in the work of an engineer. Acquiring knowledge in the field of creating diagrams and design documentation of power, control and signaling systems using the EPLAN Electric P8 design support program. Acquiring the ability to create technical documentation in an efficient and transparent manner.							
Course content	Lecture: Characc electric applica Electric creating project schema process dimens specific Specialistit Designi cables, control	teristics al instal tions he P8). Or g contro manage atics, ter sing con ioning, v cations, c	of comm lation an lpful in th verview of systems ment, pr minals, of nponents working v installation wer supp circuit pro	nonly us d indust ne work of princip s. EPLA oject str cables, u , autom with mac on of the oly, cont otection of electr	ed progr rial auto of an en oles of o N Electr ucture, o using PL atic crea ros, aut cabine rol and s and sys rical and	rams for mation. gineer, (peration ic P8 ov creating .C comp ation of a omatic p t and the signaling tem com control i	creating Possibil CAE pro of autor erview: i projects onents, issembly part num mounti system ponents installati	g projects a ity of suppo grams (Co mation sys installation according editing cor y documen bering, obj ng plate.	and technical documentation in the field of orting the design with the use of selected imputer Aided Engineering, eg EPLAN item components and the principles of process, customizing the user interface, to IEC 61346/61355, creating electrical mponents from navigators, data natation, creation of graphic elements with ject-oriented planning and preparation of le electrical system. Selection of electric is of the performance of the designed the EPLAN Electric P8 program.
Teaching methods	Informa and dis	itive-pro cussion	blem lec ;	ture; Cla	asses in	compute	er metho	ods and teo	chniques with demonstration, instruction
Assessment method	Leo Spe	ture: on ecialistic	ie test c workshi	op: evalı	uation o ^r	f reports	, individı	ual progres	ss, discussion and activity at workshop
Symbol of learning outcome	<u> </u>			Lear	ning outcor	nes		. •	Reference to the learning outcomes for the field of study
			Knowledg	je: the grad	duate know	/s and und	erstands		
1 01	onoratir	na nrino	inlee of a	utomati	o control	l evetam	c		CP1 W02

LOT	operating principles of automatic control systems				
LO2	capabilities of the EPLAN Electric P8 design support program	CP1_W04			
LO3	principles of electrical stroke protection in automatic control systems	CP1_W11			
	Skills: the graduate is able to				
LO4	work individually and in a team, estimate the time needed to complete a task	CP1_U03			
LO5	design and verify the correctness of the created project	CP1 U06			
LO6	conduct a discussion on the completed project	CP1 U04			
Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition during which t assessed	ne outcome is		
L01	Lecture: one test;	W			
LO2	Lecture: one test;	W			
LO3	Lecture: one test;	W			
LO4	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		Ps		
LO5	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		Ps		
LO6	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		Ps		
	Student workload (in hours)	No. of hours			
	Lecture attendance	15			
	Workshop attendance	30			
	Preparation for lecture test(s)	9			
Calculation	Preparation for specialistic workshop	12			
	Preparation for workshop completion	4			
	Participation in teacher-student sessions related to the module subject	5			
	Participation in teacher-student sessions related to the module subject TOTAL	5 75			
	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators	5 75 Hours	ECTS		
	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation	5 75 Hours 50	ECTS 2		
	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities	5 75 Hours 50 51	ECTS 2 2		
Basic references	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities 1. Dominik I., Tworzenie dokumentacji technicznej w programie EPLAN 2012.	5 75 Hours 50 51 – przykłady praktyczne,	ECTS 2 2 Kraków		
Basic references	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities 1. Dominik I., Tworzenie dokumentacji technicznej w programie EPLAN 2012. 2. Gischel B., EPLAN Electric P8 Reference Handbook, Hanser, Carl G	5 75 ^{Hours} 50 51 - przykłady praktyczne, mbH+Co., 2016.	ECTS 2 2 Kraków		
Basic references	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities 1. Dominik I., Tworzenie dokumentacji technicznej w programie EPLAN 2012. 2. Gischel B., EPLAN Electric P8 Reference Handbook, Hanser, Carl G 1. Rengstorf J., EPLAN electric P8 - Version 2. Schülerband, Bildungsv	5 75 Hours 50 51 – przykłady praktyczne, mbH+Co., 2016. erlag Eins GmbH, 2017.	ECTS 2 2 Kraków		
Basic references	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities 1. Dominik I., Tworzenie dokumentacji technicznej w programie EPLAN 2012. 2. Gischel B., EPLAN Electric P8 Reference Handbook, Hanser, Carl G 1. Rengstorf J., EPLAN electric P8 - Version 2. Schülerband, Bildungsv 2. Meinert F., EPLAN Electric P8 für Dummies, Wiley VCH Verlag Gmb	5 75 Hours 50 51 - przykłady praktyczne, mbH+Co., 2016. erlag Eins GmbH, 2017. H, 2019.	ECTS 2 2 Kraków		
Basic references Supplementary references	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities 1. Dominik I., Tworzenie dokumentacji technicznej w programie EPLAN 2012. 2. Gischel B., EPLAN Electric P8 Reference Handbook, Hanser, Carl G 1. Rengstorf J., EPLAN electric P8 - Version 2. Schülerband, Bildungsv 2. Meinert F., EPLAN Electric P8 für Dummies, Wiley VCH Verlag Gmb 3. Dokumentacja techniczna programu EPLAN: www.eplan.pl, www.epl	5 75 Hours 50 51 – przykłady praktyczne, mbH+Co., 2016. erlag Eins GmbH, 2017. H, 2019. anusa.com	ECTS 2 2 Kraków		
Basic references Supplementary references	Participation in teacher-student sessions related to the module subject TOTAL Quantitative indicators Student workload - activities that require direct teacher participation Student workload - practical activities 1. Dominik I., Tworzenie dokumentacji technicznej w programie EPLAN 2012. 2. Gischel B., EPLAN Electric P8 Reference Handbook, Hanser, Carl G 1. Rengstorf J., EPLAN Electric P8 - Version 2. Schülerband, Bildungsv 2. Meinert F., EPLAN Electric P8 für Dummies, Wiley VCH Verlag Gmb 3. Dokumentacja techniczna programu EPLAN: www.eplan.pl, www.epl 4. Internetowe materiały firmowe: www.automatykaonline.pl, www.forun	5 Hours 50 51 - przykłady praktyczne, mbH+Co., 2016. erlag Eins GmbH, 2017. H, 2019. anusa.com nsep.pl	ECTS 2 2 Kraków		

Author of the programme	dr inż. Adam Kuźma	2022-06-07
1 - 5		

				Bia	ystok U	Iniversi	ty of Te	chnology		
				Fa	culty of	Electri	cal Eng	ineering		
Field of study			Industi	y Digit	ization			and programme		full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile		general academic
Course name		С	ompute	r aided	desian	2		Course code		CP1S03004
	g				Course type		obligatory			
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester		3
educational ectivities	15				30			No. of ECTS credits		3
Entry requirements				Technic	al drawi	ng, Mecl	hanical	component	ts and	l subsystems
Course objectives	Acquain product and ser CAD m Acquirin use of r	Acquainting with the functionalities of selected CAx tools for the design, visualization, engineering analysis, production and quality control of mechanical assemblies of open and closed kinematic chains of industrial and service robots, as well as automated systems. Analysis of the possibility of using solid and surface CAD models to design single parts and assemblies of devices used in flexible manufacturing systems. Acquiring practical skills in operating programs for the design of technical objects and their analysis with the use of modern modeling methods and CAD/CAE computer simulation.								
Course content	Introduces support techniq functior method database form of Specialisti Create solutior Perform	ction to t ting com ues, app nality to l of finite ses and technica c workshop and edit ns. Deve ning mec	he probl puter de blications be used elemen other co al drawin models lopment chanical	ems of o sign of r s, advan in engin ts in selo mputer a gs base of parts of detai analysis	compute nachine tages ar eering p ected C/ aided de d on the Prepar- led draw of a se	r aided of s and de nd disad practice. AE tools sign pro tools made 3 ation of a vings of p	design o evices. S vantage Creatior . PLM, F ocess ap BD mode a projec parts an ned robo	of mechanic Solid and su s. CAx pro n of analysi PDM and C plications. els. t of a robot d assembly tic assembly	cal ele urface grams is of e IM sy Creat creat creat drav	ements. Analysis of environments e modeling - the essence of s - areas of their application and engineering projects using the rstems. Generators, toolboxes, ting design documentation in the sembly based on a review of existing wings of the designed device.
Teaching methods	Informa and dis	itive-prol cussion;	olem lec	ture; Cla	isses in	compute	er metho	ods and teo	chniqu	ues with demonstration, instruction
Assessment method	Leo	ture: on	e test		untion of	roporto	individ		n dia	oussion and activity of workshop
Symbol of learning outcome	Spi		WUIK5III	Lear	ning outcor	nes	, וועויועו		55, 015	Reference to the learning outcomes for the field of study
			Knowledg	e: the grad	luate know	vs and und	erstands			
L01	CAD of	surface	and soli	d model	ing					CP1 W02 CP1 W05

LO2	purposes and principles of engineering analyzes in CAD/CAE packages	CP1_W12	CP1_W05	
LO3	applications and basic functionalities of CAI tools	CP1 W12		
	Skills: the graduate is able to			
LO4	model and edit solid models	CP1 U02		
LO5	make assemblies from individual parts	CP1 U04		
LO6	determine physical properties of a solid object and analyze the motion of a robotic assembly	CP1_U10	CP1_U04	
	Social competences: the graduate is ready to			
LO7	critical assessment of knowledge, self-education and improvement of qualifications, use of own knowledge and experts opinions in order to solve various problems	CP1_K01		
LO8	take responsibility for the consequences of using the designed robotic component	CP1_K03		
Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition of	during which th assessed	ne outcome is
LO1	Lecture: one test;	W		
LO2	Lecture: one test;	W		
LO3	Lecture: one test;	W		
LO4	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;			Ps
LO5	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;			Ps
LO6	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;			Ps
LO7	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;			Ps
LO8	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;			Ps
	Student workload (in hours)		No. of hours	
	Lecture attendance		15	
	Workshop attendance		30	
	Preparation for lecture test(s)		9	
Calculation	Preparation for specialistic workshop		12	
	Preparation for workshop completion		4	
	Participation in teacher-student sessions related to the module subject		5	
	TOTAL		75	
	Quantitative indicators	Hour	S	ECTS
	Student workload - activities that require direct teacher participation	50		2
	Student workload - practical activities	51		2

	1. Łodygowski T., Kąkol W., Metoda elementów skończonych w wybranych zagadnieniach mechaniki konstrukcji inżynierskich, Politechnika Poznańska 2003.									
	2. Keska P., SolidWorks 2013, Modelowanie części, złożenia, rysunki, Wydawnictwo CADvantage, 2013.									
Basic references	3. Kurmaz L., Kurmaz O., Podstawy konstruowania węzłów i części maszyn: podręcznik konstruowania, 2011.									
	4. Przybylski W., Deja M., Komputerowo wspomagane wytwarzanie maszyn: podstawy i zastosowanie, WNT, Warszawa 2007.									
	5. Chlebus E., Techniki komputerowe CAx w inżynierii produkcji, WNT, Warszawa, 2004.									
	1. Czasopisma branżowe (np., Design News Polska, Projektowanie i Konstrukcje Inżynierskie).									
	2. Lombard M., SolidWorks 2011 Parts Bible, Wiley Publishing, 2011.									
Supplementary references	3. Lombard M., SolidWorks 2011 Asemmblies Bible, Wiley Publishing, 2011.									
Telefendes	4. SolidWorks Rysunki, Wydawnictwo CNS Solutions, 2012.									
	5. Portale internetowe (np., www.3dcad.pl, www.solidworks.com, www.cns.pl).									
Organisational unit conducting the course	Department of Automatic Control and Robotics	Date of issuing the programme								
Author of the programme	dr inż. Roman Trochimczuk	2022-06-07								

				Bia	lystok l	Iniversi	ty of Te	chnology	
				Fa	iculty of	fElectri	cal Eng	ineering	
Field of study			Indust	ry Digit	ization	I		and programme	full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile	general academic
			Duthan					Course code	CP1S03005
Course name			Python	prograi		2		Course type	obligatory
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities					30			No. of ECTS credits	2
Entry requirements						Pythe	on progr	ramming 1	
Course objectives	Acquisi and de	ition of s sign of r	kills in th obots, pr	ie use o rogramm	f advand ning of h	ced lang ardware	uage co support	nstructs, th in Python.	ne use of libraries supporting the analysis
Course content	Specialisti The use concuri Pybotic	c workshop e of adva rency. A cs. Hardv	anced st pplicatio ware sur	ructures n of libra port pro	of the F aries sur grammin	Python la oporting ng in Pyf	anguage the anal thon, e.ç	, including: lysis and de g.: Raspber	: iterators and generators, co-programs, esign of robots, e.g.: DART, PyDy, rry PI, STM32.
Teaching methods	Specia	lization v	workshor	p;					
Assessment method	Spe	ecialistic	worksh	op: eval	uation of	f reports	, individ	ual progres	s, discussion and activity at workshop
Symbol of learning outcome				Lear	rning outcor	mes			Reference to the learning outcomes for the field of study
	<u> </u>			Skills: the	e graduate	is able to			
LO4	use adv	vanced F	Python c	onstruct	is				CP1 U07
LO5	use libr	aries su	pporting	the ana	lysis an	d design	of robo	ts in Pytho	CP1_U06 CP1_U07
LO6	prograr	n hardw	are supp	port in P	ython				CP1 U07 CP1 U08
			Social (competenc	es: the gra	aduate is re	ady to		
LO7	respon	sible pla	nning of	activitie	s related	d to the p	preparat	ion for clas	ses CP1_K03
LO8	conduc	t progra	mming a	ctivities	in a cre	ative wa	у		CP1 K04
Symbol of learning outcome			Method	ls of asses	sing the le	arning out	comes		Type of tuition during which the outcome is assessed
LO4	Special discus:	listic wor sion and	rkshop: e activity	evaluation at works	on of rep shop;	orts, ind	ividual p	orogress,	Ps
LO5	Special discus:	listic wor sion and	rkshop: e activity	∍valuatio at works	on of rep shop;	orts, ind	ividual p	orogress,	Ps

LO6	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		Ps							
LO7	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;									
LO8	Specialistic workshop: evaluation of reports, individual progress, discussion and activity at workshop;		Ps							
	Student workload (in hours)	No. of hours								
	Workshop attendance	30								
	Preparation for specialistic workshop	11								
Calculation	Preparation for workshop completion	4								
	Participation in teacher-student sessions related to the module subject	5								
	TOTAL	50								
	Quantitative indicators	Hours	ECTS							
	Student workload - activities that require direct teacher participation	35	1,4							
	Student workload - practical activities	50	2							
	1. Gorelick M., Ozsvald I., Wysokowydajny Python: efektywne program Gliwice 2021.	owanie w praktyce. Helio	n: O'Reilly,							
Basic references	2. Ramalho L., Zaawansowany Python. Jasne, zwięzłe i efektywne programowanie. APN Promise: O'Reilly, Warszawa 2015.									
	3. Hillard D., Python: dobre praktyki profesjonalistów. Helion, Gliwice 2020.									
	4. Staple D., Jak zaprogramować robota: zastosowanie Raspberry PI i Pythona w tworzeniu autonomicznych robotów. Helion, Gliwice 2022.									
	1. Monk S., Raspberry PI: przewodnik dla programistów Pythona. Helio	n, Gliwice 2014.								
Supplementary	2. https://dartsim.github.io/									
references	3. https://github.com/pydy/pydy									
	4. https://pypi.org/project/pybotics/									
Organisational unit conducting the course	Department of Automatic Control and Robotics	Date of issuing the programme								
Author of the programme	dr hab. inż. Zbigniew Kulesza, prof. PB	2022-06-07								

				Bial	lystok U	niversit	y of Te	chnology		
				Fa	culty of	Electric	cal Eng	ineering		
Field of study			Industr	ry Digit	ization			and programme		full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile		general academic
Course name		Г)inital si	anal pr	ocessin	a		Course code		CP1S03006
				gilai pr		9		Course type		obligatory
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester		3
educational ectivities	15		30					No. of ECTS credits		4
Entry requirements					Ν	lathema	tics 1, N	lathematic	s 2	
Course objectives	Acquair domain possibil with acc	nting wit s and ol lities of l quiring t	h the me otaining hardware he skills	ethods o practical and so of their	f signal a l skills in ftware in design a	analysis this fiel nplemen nd imple	and dig d. Acqua tation o ementat	ital signal p ainting with f basic met ion.	oroce h the thods	essing systems in time and frequency methods of synthesis and the of digital signal processing, along
Course content	Lecture: Areas of respons filters. T implem system: fast Foi system: respons Basic s Laboratory Samplir Time ar with fini Design filter ch	of applicates filters Fhe use entation s. Samp urier trans in time se, trans tructure: relasses: ng and c nd frequ te and in and imp aracteris	ation of c . Realiza of softwa of digita ling and sform. A and free for funct s of signa quantizat ency cha nfinite im plementa stics.	digital sig ability, ca are for fi al signal quantize (quantize apuency of al proce al proce al proce an of si aracteris apulse re- tion of d	gnal pro- ausality, Iter synti process ation. Sp of the pr domains uency c ssing cir gnals. T tics of b esponse ligital filt	cessing stability hesis an ing meth bectrum actical u : differer haracter rouits an ime and asic type - charac ers with	methods . Overvi d praction ods. Ex analysis use of FF ntial equ istics, so d their fe spectra es of dig theristics the use	s. Signal cl ew of analy cal aspects amples of of signals T. Basic n ations, app ate variable atures; I analysis of ital filters. of signal p	assif ysis a s of h appli ; use nethc blicati les. D bf sig Synth s, app roces	ication. Finite and infinite impulse and synthesis methods of digital ardware and software cations and realizations in industrial of Fourier transform. Discrete and ods of description of signals and ion of the Z transform, impulse Discrete linear and cyclic convolution.
Teaching methods	Informa	tive-pro	blem lec	ture; Lal	ooratory	classes				
Assessment method	Lec Lab	ture: ex	am evaluati	ion of int	troductor	ry tests,	reports,	discussior	n and	activity during the classes
Symbol of learning outcome				Lear	ning outcor	nes				Reference to the learning outcomes for the field of study

	Knowledge: the graduate knows and understands		
LO1	methods of signal analysis in time and frequency domains	CP1 W09	
LO2	principles of analog-to-digital conversion and selection of parameters of this process	CP1_W09	
LO3	description, analysis, synthesis and implementation methods of digital signal processing systems	CP1_W04 CP1	_W09
	Skills: the graduate is able to		
LO4	analyze signals in time and frequency domains, using appropriate hardware and software tools	CP1_U06 CP1	_U11
LO5	formulate the specification of digital signal processing systems, perform their synthesis and verification using computer-aided design tools	CP1_U06	
LO6	perform hardware implementation of simple digital signal processing systems and measure their characteristics	CP1_U06 CP1	_U08 CP1_U
Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition during asse	g which the outcome essed
L01	Lecture: exam;	W	
LO2	Lecture: exam;	W	
LO3	Lecture: exam;	W	
LO4	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	L	
LO5	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	L	
LO6	Laboratory: evaluation of introductory tests, reports, discussion and activity during the classes;	L	
	Student workload (in hours)	No. o	of hours
	Lecture attendance		15
	Laboratory classes attendance		30
	Preparation for the lecture exam; participation in the exam		25
Calculation	Preparation for laboratory classes		19
	Preparation for laboratory classes completion		6
	Participation in teacher-student sessions related to the module subject		5
	TOTAL	1	00
	Quantitative indicators	Hours	ECTS
	Student workload - activities that require direct teacher participation	52	2,1
	Student workload - practical activities	60	2,4
	1. Lyons R., Wprowadzenie do cyfrowego przetwarzania sygnałów. WK	Ł, Warszawa, 201	0.
	2. Owen M., Przetwarzanie sygnałów w praktyce, WKŁ, Warszawa, 200)9.	
	3. Zieliński T., Cyfrowe przetwarzanie sygnałów: od teorii do zastosowa	ań. WKŁ, Warszaw	va, 2009.
Basic references	4. Smith S. W., Cyfrowe przetwarzanie sygnałów: praktyczny poradnik Warszawa, 2007.	dla inżynierów i na	ukowców, BTC,

	5. Osowski S., Cyfrowe przetwarzanie sygnałów z zastosowaniem M Politechniki Warszawskiej, Warszawa, 2016.	ATLABA, Oficyna Wydawnicza							
	1. Szabatin J., Podstawy teorii sygnałów. WKŁ, Warszawa, 2007.								
Supplementary references	2. Zieliński T. (red.), Cyfrowe przetwarzanie sygnałów w telekomunikacji: podstawy, multimedia, transmisja, PWN, Warszawa, 2014.								
	3. Leśnicki A., Technika cyfrowego przetwarzania sygnałów, Wydawnictwo Politechniki Gdańskiej, Gdańsk, 2016.								
	4. Manolakis D. G., Ingle V. K., Applied digital signal processing: theory and practice, Cambridge University Press, Cambridge, 2011.								
	5. Rao K. D., Swamy M. N. S., Digital Signal Processing. Theory and	Practice, Springer, 2018.							
Organisational unit conducting the course	Department of Photonics, Electronics and Light Technology	Date of issuing the programme							
Author of the programme	dr hab. inż. Dariusz Jańczak	2022-06-07							

				Bia	lystok L	Jniversi	ty of Te	chnology	
				Fa	culty of	fElectri	cal Eng	lineering	
Field of study			Indust	ry Digit	ization	1		and programme	full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile	general academic
Course name		Materi	ials nro	ressing	techno	logies		Course code	CP1S03007
		Water		cessing		logies		Course type	obligatory
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities	15							No. of ECTS credits	1
Entry requirements					3D pro	ototyping	and ad	ditive manu	ufacturing
Course objectives	Acquai of engli Electro Presen materia cycle o layers. methoc (constri (thermo of shap (plastic	nting wit neering r technolo tation of als. Prese f engine Acquain Is of proo uction, a pplastic, pforming ping cera s, machir	n basic i materials gies use basic to entation ering ma ting with duction a dhesive duroplas , fillers, j mic and hing and	ssues o s. Additiv ed in ma ols in m of issue aterials. basic to and mod , coating stic and pigments glass m thermal	ve techn terials p aterials s of eco Materials echnique lification g, synthe elastom s, dyes, naterials process	re and p liques. N rocessin research nomy ar s recircu es of ma of nano etic fibers leric). Po softener . Cerami sing, four	ropertie lethods ng. Over n. Provid nd time- ilation p nufactu materia s, specia lymeriza 's, stabil c compo nding, w	es of engine of producir view of the de an overv consuming rocesses. T ring and pro ls. Classific al). Overvie ation and p lizers, antis osites. Disc velding). Su	eering materials. Overview of basic groups ing composite materials. e applications of laser treatment. view of the most important functional methods of material processing. Life Technology for the production of thin occessing materials. Discussion of cation of polymers by application ew of the classification of polymers processing methods of polymer materials static agents). Presentation of the methods cussion of metal materials and their alloys urface engineering.
Course content	Lecture: Constru- techniq Electro function materia Techno Nanom special glass n foundin	uction ar lues. Bas technolo nal mate als proce blogy for laterials.). Types naterials ng, weldi	Id prope sic tools igies use rials and ssing m the proc Classifi of polyr . Cerami ng). Sur	rties of e in the s ed in ma the bas ethods. luction of cation of ners. Pro ic compo face eng	engineer tudy of r terials p sics of th Life cycl of thin lay f polyme ocessin(osites. N jineering	ing mate naterials rocessin le of eng yers. Ter yers by ap g methoo Aetals ar	erials. B a. Metho ng. Lase uction. I ineering chnolog plication ds of po nd alloys	asic group ods of produ er processin Economica g materials. ies for the n (construc lymer mate s (plastic, m	of engineering materials. Additive ucing composite materials. ng. Overview of the most important I, ecological and time-consuming . Materials recirculation processes. production and processing of materials. tion, adhesive, coating, synthetic fibers, erials. Methods of shaping ceramic and machining and heat working processes,
Teaching methods	Informa	ative-prol	blem lec	ture;					
Assessment method	Leo	cture: on	e test						

Symbol of learning outcome	Learning outcomes	Reference to the learning outcome study	es for the field of							
	Knowledge: the graduate knows and understands									
LO1	basic materials processing	CP1 W12								
LO2	principles of selection and application of engineering materials	CP1_W12								
LO3	processes of using and designing the flow of materials in industrial processes	CP1_W13								
Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition during which th assessed	e outcome is							
LO1	Lecture: one test;	W								
LO2	Lecture: one test;	W								
LO3	Lecture: one test;	W								
	Student workload (in hours)	No. of hours								
	Lecture attendance	15								
Calculation	Preparation for lecture test(s)	5								
Odiodidion	Participation in teacher-student sessions related to the module subject	5								
	TOTAL	25								
	Quantitative indicators	Hours	ECTS							
	Student workload - activities that require direct teacher participation	20	0,8							
	Student workload - practical activities	0	0							
	1. Dobrzański L., Metalowe materiały inżynierskie. Wydawnictwa Nauko	owo-Techniczne WNT, 20	04.							
	2. Blicharski M., Wstęp do inżynierii materiałowej. Wydawnictwo WNT,	2003.								
	3. Ashby M., Shercliff H., Cebon D., Inżynieria materiałowa T1, T2. Galaktyka, 2011.									
Basic references	 Dobrzański L. A., Zasady doboru materiałów inżynierskich z kartami charakterystyk. Politechnika Śląska, Gliwice 2001. 									
	5. Szlezyngier W., Brzozowski Z. K., Tworzywa sztuczne: chemia, technologia wytwarzania, właściwości, przetwórstwo, zastosowanie. T. 2, Polimery specjalne i inżynieryjne. Wydawnictwo Oświatowe FOSZE, Rzeszów 2012.									
	1. Kula P., Inżynieria Warstwy Wierzchniej. Wydawnictwo Politechniki Łódzkiej. Łódź 2000. 2. Grabski M. W., Kozubowski J. A., Inżynieria materiałowa. Geneza, istota, perspektywy, Oficyna Wydawnicza Politechniki Warszawskiej, 2003.									
Supplementary references	 Rabek J. F., Współczesna wiedza o polimerach. 2, Polimery naturalr zastosowania. Wydawnictwo Naukowe PWN, Warszawa 2017. 	ne i syntetyczne, otrzymyw	vanie i							
	 Zimny J., Laserowa obróbka stali. Wydawnictwo Politechniki Częstow Jurczyk M., Nanomateriały: wybrane zagadnienia. Politechnika Pozna 	chowskiej, Częstochowa ańska, Poznań 2001.	1999.							
Organisational unit conducting the course	Department of Photonics, Electronics and Light Technology	Date of issuing the programme								
Author of the programme	dr hab. inż. Piotr Miluski, prof. PB	2022-06-07								

				Bia	lystok L	Iniversi	ty of Te	chnology	
				Fa	culty of	fElectri	cal Engi	ineering	
Field of study			Industr	ry Digit	ization	1		and programme	full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile	general academic
Course name			Foreic	nn lana	2 909			Course code	CP1S03008
				Jii lang.	Jaye 2			Course type	elective
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities		30						No. of ECTS credits	2
Entry requirements						For	eign lan	guage 1	
Course objectives	Continu above i about fi basic v	ie to imp n line wi undamei ocabulai	orove lan ith the Co ntal diler ry of the	guage p ommon nmas of field of	Forficient Europea modern study. F	cy (lister an Frame i civilizat amiliariz	ing, rea work of tion and ation wif	iding, intera Reference issues of t th the selec	acting, production, writing) at level B2 or for Languages. Stimulating curiosity he field of study. Getting to know the cted type of specialist text.
Course content	Classes: Topics problen related card, pi	related t ns of the to the fie roject do	to acade studied eld of stu ocumenta	mic life, field. La Jdy. Wor ation).	current anguage rk with a	problem and gra selecte	s of soci .mmar is d type of	ial life and sues in the f specialist	dilemmas of modern civilization and discussed texts. Basic vocabulary text (e.g. technical specification, catalog
Teaching methods	Classe	s;							
Assessment method	Eva	aluation	of inter-s	semeste	r tests; r	nodular	tests, wr	ritten and o	ral statements
Symbol of learning outcome				Lear	rning outcor	mes			Reference to the learning outcomes for the field of study
				Skills: the	e graduate	is able to			
LO4	underst that the terminc	and and y relate logy in t	l formula to a well he field (te oral s l-known of the st	tatemer subject, udied fie	its to a g , also thc eld	reater e	xtent, prov aining basi	ded CP1_U01 CP1_U04 CP1_U05
LO5	underst the moo the field	and and: dern wor d of stud	l formula 1d, inclue ly	te to a g ding tho	jreater e se conta	xtent tex aining the	(ts on va e basic t	arious issue terminology	es of CP1_U01 CP1_U05
LO6	underst	and and	l interpre	t the se	lected ty	/pe of sp	ecialist	text	CP1 U01 CP1 U05
			Social of	competenc	es: the gra	aduate is re	ady to		
LO7	take an expres:	active p sed opin	bart in the	e discus ws, cult	sion res ural refe	pecting rences	the dive	rsity of	CP1_K02

Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition during which the assessed	ne outcome is							
LO4	Evaluation of inter-semester tests; modular tests, written and oral statements;	С								
LO5	Evaluation of inter-semester tests; modular tests, written and oral statements;	С								
LO6	Evaluation of inter-semester tests; modular tests, written and oral statements;	С								
LO7	Evaluation of inter-semester tests; modular tests, written and oral statements;	С								
	Student workload (in hours)	No. of hours								
	Classes attendance	30								
	Preparation for classes	9								
Calculation	Preparation for classes completion	6								
	Participation in teacher-student sessions related to the module subject	5								
	TOTAL	50								
	Quantitative indicators	Hours	ECTS							
	Student workload - activities that require direct teacher participation	35	1,4							
	Student workload - practical activities	50	2							
Basic references	 Cieplicka M., Torzewska W., Русский язык. Kompendium tematyczno-leksykalne 2, Wagros 2008. Długokęcka J., Chadaj S., Język niemiecki zawodowy w branży elektronicznej, informatycznej i elektrycznej, WSIP 2013. McCarthy M., Academic Vocabulary in Use, Cambridge: Cambridge University Press 2010. Chwatow S., Hajczuk R., Русский язык в бизнесе, WSiP 2000. Kuhn Ch., Niemann R. M., Winzer-Kiontke B., Studio d - Die Mittelstufe B2, Cornelsen Verlag 2010. 									
	7. Foley M., My Grammar Lab, Pearson 2012. 8. Granatowska H., Danecka I., Как дела? 2. Wyd. Szkolne PWN 2003. 9. Koithan U., Schmitz H., Sieber T., Sonntag R., Aspekte Mittelstufe Deutsch, Langenscheidt 2007.									
	 Milczarek W., Język rosyjski od A do Z. Repetytorium, Kram. 2007. Longman Dictionary of Contemporary English. Harlow: Pearson Education 2011. Kowalska N., Samek D., Praktyczna gramatyka języka rosyjskiego, REA 2004. Nietrzebka M., Ostalak S., Alles klar Grammatik, WSIP 2004. 									
Supplementary	 Kuca Z., Język rosyjski w biznesie dla średniozaawansowanych, WSiP 2007. Kostka G., Elektroniker fuer Energie- und Gebaeudetechnik, Fundacja VCC. 									
references	 6. Samek D., Rozmówki polsko-rosyjskie, REA 2009. 7. Słownik naukowo-techniczny polsko-niemiecki, niemiecko-polski. WN 	NT 2006, 2007.								
	 Słownik naukowo-techniczny rosyjsko-polski. WNT 2009. Corbeil J-C., Archambault A., Wielojęzyczny słownik wizualny, leksykon tematyczny, Wydawnictwo Wilga 1996. 									

Organisational unit conducting the course	School of Foreign Languages	Date of issuing the programme
Author of the programme	mgr Dorota Ostrowska	2022-06-07

				Bia	lystok U	Iniversi	ty of Te	chnology	
				Fa	culty of	Electri	cal Eng	ineering	
Field of study			Industr	y Digit	ization			and programme	full-time Bachelor's degree
Specjalization / diploma path			com	mon su	bject			Study profile	general academic
Course name		Inte	lectual r	oropert	v protec	tion		Course code	CP1S03009
					,			Course type	elective
Forms and number of hours of	L	С	LC	Р	SW	FW	S	Semester	3
educational ectivities	15							No. of ECTS credits	1
Entry requirements							-		
Course objectives	Discuss at the n configu of pater intangit	sion of th ational, ration of nt protec ble good	ne legal l commur integrate tion and s protect	bases of ity and i ed circu the pro- ted by la	f copyrig internation its and p cedure c aw. Obta	ht as we onal leve protection of obtaini ining inf	ell as inte el. Legal n of soft ing pate ormatior	ellectual pater l and pater ware and c nts. Explar n on patent	roperty and patent protection regulations at protection of material goods, databases. Acquainting with the strategies nation of the rules of using tangible and ts.
Course content	Lecture: Basic c things, and em Unfair (procedu rights. I of intell rights a protecti	oncepts concept ployee v Competit ures (nat Vanagin ectual pr nd perso on of so	of intelle of innov works. Pr tional, in g industr roperty la onal righ ftware a	ectual pr ation, w rotectior eements ternatior rial and aw in Pc ts. Indus nd datat	roperty p ork, pate of intell s used in nal). Pate intellectu pland, Eu strial pro pases. P	protection ents, util lectual p on the trace ent data ual prope uropean perty law rerequis	n: the co ity mode property de of inte bases: r erty. Pre and inte v. Indus ites for p	oncept of c els, industr in the light ellectual pr national, in mises of p ernational la trial proper protection	reator, intellectual property, property of y designs owe, trademarks. Co-authorship of university law. The Act on Combating operty rights. Patent application ternational. Patent Claims. Exclusive rotection of innovative solutions. Sources aw. Copyright and related rights. Property ty law and copyright protection. Legal resulting from copyright.
Teaching methods	Informa	itive-prot	blem lec	ture;					
method	Leo	ture: on	e test						
Symbol of learning outcome				Lear	ning outcor	nes			Reference to the learning outcomes for the field of study
			Knowledg	e: the grad	duate know	/s and und	erstands		
LO1	basic c	oncepts	of the in	tellectua	al proper	ty prote	ction		
LO2	basic p	rinciples	of indus	strial pro	perty lav	w and co	pyright	law	CP1 W13
LO3	rules of	using ta	angible a	ind intar	igible go	ods pro	tected by	y law	CP1_W13

Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition during which th assessed	e outcome is							
LO1	Lecture: one test;	W								
LO2	Lecture: one test;	W								
LO3	Lecture: one test;	W								
	Student workload (in hours)	No. of hours								
	Lecture attendance	15								
Colculation	Preparation for lecture test(s)	5								
Calculation	Participation in teacher-student sessions related to the module subject	5								
	TOTAL	25								
	Quantitative indicators	Hours	ECTS							
	Student workload - activities that require direct teacher participation	20	0,8							
	Student workload - practical activities	0	0							
	1. Pyrża A., Poradnik wynalazcy. Urząd Patentowy RP, Warszawa, 201	7.								
	2. Rzężelewska D., Własność intelektualna dla przedsiębiorcy. Urząd Patentowy RP, Warszawa, 2020.									
Basic references	3. Markiewicz R., Ilustrowane prawo autorskie. Wolters Kluwer Polska, Warszawa, 2018.									
	4. Przewodnik dla eksperta ochrony własności intelektualnej, NCBR, W	′arszawa, 2017.								
	5. Nowak–Gruca A., Własność intelektualna w przedsiębiorstwie, Gdań	isk: ODDK Sp. o.o. Sp.k, 2	2018.							
	1. Ustawa z dnia 4 lutego 1994 r. o prawie autorskim i prawach pokrewnych (Dz. U. 2021. poz. 1062 z późn. zm.).									
	2. Ustawa z dnia 30 czerwca 2000 r. Prawo własności przemysłowej (Dz.U.2001 nr 49 poz. 508 z późn. zm.).									
Supplementary references	3. Ustawa z dnia 16 kwietnia 1993 r. o zwalczaniu nieuczciwej konkurencji, (Dz.U. 2021 poz. 1655 z późn. zm.).									
	4. du Vall M., du Vall P., Kostański P., Ożegalska-Trybalska J., Podrec Prawo patentowe. Wolters Kluwer Polska, 2017.	ki P., Traple E., Uchańska	a Joanna,							
	5. Michniewicz G., Ochrona własności intelektualnej, C.H.BECK, 2016.									
Organisational unit conducting the course	Department of Electrical Engineering, Energoelectronics and Electroenergetics	Date of issuing the programme								
Author of the programme	dr hab. inż. Bogusław Butryło, prof. PB	2022-06-07								

				Bia	lystok U	niversit	y of Te	chnology					
				Fa	culty of	Electric	cal Engi	ineering					
Field of study			Industi	ry Digit	ization			and programme	full-time Bachelor's degree				
Specjalization / diploma path	common subject						Study profile	general academic					
Course name	l egal aspects of industry digitization							Course code	CP1S03010 elective				
							Course type						
Forms and number of hours of educational ectivities	L	С	LC	Р	SW	FW	S	Semester	3				
	15							No. of ECTS credits	1				
Entry requirements							-						
Course objectives	Overvie procedu law. Pro digital o technol univers principl	ew of co ure of ob esentatio devices. ogy. Prin al desig es of su	oyright la otaining p on of issu Discuss nciples c n in the f stainable	aw and p patents. ues relation of th of assem field of te e develo	patent pr Explana ted to sc e securi ably and echnical pment a	otection tion of th ftware li ty issues arrange solution s part of	Acquaine rules censing s of data ment of s in the solutior	nting with t of using ta , legal restrin storage, s electrical d field of ind ns in the fie	ng with the strategies of patent protection and the using tangible and intangible goods protected by gal restrictions applied by manufacturers of orage, securing data sets, the use of cloud ectrical devices. Overview of the principles of Id of industry digitization. Implementation of the in the field of industry digitization.				
Course content	Lecture: Premises of protection of technical and IT solutions. Basic terms in the field of intellectual property protection: creator, intellectual property, property of things, innovation, work, patent. Security, data consistency in cloud technologies. Legal restrictions by device manufacturers. Ergonomics and principles of device construction: principles of the arrangement of electrical devices, principles of the arrangement of control and monitoring devices. Influence of digital technologies on ergonomics of workplaces. Ergonomics in cyber-physical systems. Ergonomic workstations in a human-machine cooperation system. Principles of universal design in the field of industry digitization technology. Sustainable development: goals and principles, examples of implementing the principles. Intellectual property law. Copyright, property law, industrial property. Protection of intellectual property in the light of university law. Agreements used in the trade of intellectual property rights. Patent application procedures. Patent databases: national, international. Managing industrial and intellectual property. Legal protection of software and databases.												
Teaching methods	Informa	itive-pro	blem lec	ture;									
Assessment method	Leo	ture: on	e test										
Symbol of learning outcome				Lear	ning outcor	nes			Reference to the learning outcomes for the field of study				

r											
	Knowledge: the graduate knows and understands										
LO1	basic concepts for the protection of intellectual property	CPT W13									
LO2	basic principles of industrial property law and copyright, principles of using goods protected by law	CP1_W13									
LO3	basic data security principles	CP1 W13									
Symbol of learning outcome	Methods of assessing the learning outcomes Type of tuition during which the outco assessed										
LO1	Lecture: one test;	W									
LO2	Lecture: one test;	W									
LO3	Lecture: one test;	W									
	Student workload (in hours)	No. of hours									
Calculation	Lecture attendance	15									
	Preparation for lecture test(s)	5									
	Participation in teacher-student sessions related to the module subject	5									
	TOTAL	25									
	Quantitative indicators	Hours	ECTS								
	Student workload - activities that require direct teacher participation	20	0,8								
	Student workload - practical activities										
	1. Pyrża A., Poradnik wynalazcy. Urząd Patentowy RP, Warszawa, 2017.										
	2. Rzężelewska D., Własność intelektualna dla przedsiębiorcy. Urząd Patentowy RP, Warszawa, 2020.										
	3. Markiewicz R., Ilustrowane prawo autorskie. Wolters Kluwer Polska, Warszawa, 2018.										
Basic references	4. Dotson C., Bezpieczeństwo w chmurze. Przewodnik po projektowaniu i wdrażaniu zabezpieczeń. PWN, 2020.										
	5. Ignac-Nowicka J., Ergonomia i higiena przemysłowa. Wykłady. Wydawnictwa Politechniki Śląskiej, 2017.										
	1. Ustawa z dnia 4 lutego 1994 r. o prawie autorskim i prawach pokrewnych (Dz. U. 2021. poz. 1062 z późn. zm.).										
Supplementary references	2. Ustawa z dnia 30 czerwca 2000 r. Prawo własności przemysłowej (Dz.U.2001 nr 49 poz. 508 z późn. zm.).										
	3. du Vall M., du Vall P., Kostański P., Ożegalska-Trybalska J., Podrecki P., Traple E., Uchańska Joanna, Prawo patentowe. Wolters Kluwer Polska, 2017.										
	4. Bąk I., Cheba K., Zielona gospodarka jako narzędzie zrównoważonego rozwoju. CeDeWu Sp. z o.o., 2020.										
	5. Rogall H., Ekonomia Zrównoważonego Rozwoju, Wydawnictwo Zysk i S-ka, 2010.										
Organisational unit conducting the course	Department of Electrical Engineering, Energoelectronics and Electroenergetics										
Author of the programme	dr hab. inż. Bogusław Butryło, prof. PB	2022-06-07									