# **BIALYSTOK UNIVERSITY OF TECHNOLOGY**



Study programme

# automatic control and robotics

full-time Master's degree

seventh level of the Polish Qualifications Framework

Białystok 2019

Table of references of course outcomes to the field outcomes for master degree in *Automatic Control and Robotics* to the second degree characteristic of Polish NQF (Polskiej Ramy Kwalifikacji) levels 6-8 and universal characteristics defined in Polish law established on 22<sup>nd</sup> of December 2015 (Ustawa z dnia 22 grudnia 2015 r. o Zintegrowanym Systemie Kwalifikacji).

Explanation of the table symbols:

 $EEE1_Xxx$  – course outcomes of learning for maser degree in *Automatic Control and Robotics*, X: W – knowledge category, U – skills category, K – social competences category, xx – number of the learning outcome;

P7S – outcomes of education for master degree according to Polish NQF (Polska Rama Kwalifikacji) (qualifications achieved with higher education – LEVEL 7, general-academic profile, engineer competences).

Symbol of the learning outcome for ACR	Description of the course education outcomes – study programme <i>Automatic Control and Robotics</i> , Master degree, general-academic profile, engineering studies. After finishing studies the graduate:	Reference to the second level characteristic of Polish NQF – level 7 for technical sciences (P7S)	Reference to the second level characteristic of Polish NQF – level 7 for engineer competences					
Knowledge	Knowledge: knows and understands							
AR2_W01	in a deepened degree mathematical and physical theories, methods and models, and relationships between them in automatic control and robotics systems	P7S_WG, P7U_W	P7S_WG					
AR2_W02	in a deepened degree processes occurring in the life cycle of devices, facilities and technical systems in the field of automatic control and robotics	P7S_WG, P7U_W	P7S_WG					
AR2_W03	in a deepened degree selected facts, objects and phenomena and their methods and theories explaining the complex relationships between them in automatic control and robotics systems		P7S_WG					
AR2_W04	in a deepened degree principles of designing automatic control and robotics systems as well as supporting engineering tools and computer methods	P7S_WG, P7U_W	P7S_WG					
AR2_W05	in a deepened degree theories, methods and engineering tools necessary to manage the operation of automatic control and robotics systems	P7S_WG, P7U_W	P7S_WG					
AR2_W06	in a deepened degree principles of conducting research, experiments and simulations, analysis, interpretation and presentation of the results obtained	P7S_WG, P7U_W	P7S_WG					
AR2_W07	latest development trends in the field of automatic control and robotics	P7S_WG, P7U_W	P7S_WG					

economic, legal, ethical, civilization and other conditions of various types of activities related to automatic control and robotics principles of protection of industrial property and copyright rules for creating and developing forms of individual entrepreneurship use knowledge from various fields of science to formulate and solve complex, unusual problems, and innovatively perform and at least partially implement in practice the tasks	P7U_W P7S_WK, P7U_W P7S_WK, P7U_W	P7S_WK
rules for creating and developing forms of individual entrepreneurship use knowledge from various fields of science to formulate and solve complex, unusual problems, and innovatively	P7U_W P7S_WK, P7U_W	P7S_WK
entrepreneurship use knowledge from various fields of science to formulate and solve complex, unusual problems, and innovatively	P7U_W	P7S_WK
and solve complex, unusual problems, and innovatively	P7S HW	
and solve complex, unusual problems, and innovatively	P7S LIW	
appropriate for automatic control and robotics		P7S_UW
properly choose sources and information derived from them, make their assessment, critical analysis and synthesis, and creative interpretation and presentation of this information in the field of automatic control and robotics		P7S_UW
select and use advanced methods and tools, including information and communication techniques in automatic control and robotics systems	P7S_UW, P7U_U	P7S_UW
cognitive issues in the field of automatic control and robotics	P7U_U	P7S_UW
computer simulations, observations and theoretical	P7U_U	P7S_UW
apply the acquired knowledge in the field of automatic control and robotics to solve problems related to similar scientific disciplines	P7S_UW, P7U_U	P7S_UW
make economic assessment of the proposed technical solutions, notice their systemic and non-technical aspects in automatic control and robotics systems	P7S_UW, P7U_U	
communicate on specialist topics specific to automatic control and robotics engineer with diverse recipients, and lead the debate	P7S_UK, P7U_U	
protinsing points of the second secon	roperly choose sources and information derived from them, nake their assessment, critical analysis and synthesis, and reative interpretation and presentation of this information in he field of automatic control and robotics elect and use advanced methods and tools, including nformation and communication techniques in automatic control and robotics systems and perform research, experience or observations on ognitive issues in the field of automatic control and robotics critically evaluate the results of research, experiments, computer simulations, observations and theoretical alculations, as well as discuss measurement errors and the possibilities of optimizing the procedures used in automatic control and robotics to solve problems related to similar cientific disciplines make economic assessment of the proposed technical olutions, notice their systemic and non-technical aspects in utomatic control and robotics systems	roperly choose sources and information derived from them, nake their assessment, critical analysis and synthesis, and reative interpretation and presentation of this information in the field of automatic control and robotics       P7S_UW, P7U_U         elect and use advanced methods and tools, including promunication and communication techniques in automatic prot_U       P7S_UW, P7U_U         information and communication techniques in automatic ontrol and robotics systems       P7S_UW, P7U_U         ilan and perform research, experience or observations on ognitive issues in the field of automatic control and robotics       P7S_UW, P7U_U         critically evaluate the results of research, experiments, omputer simulations, observations and theoretical alculations, as well as discuss measurement errors and the procedures used in automatic ontrol and robotics to solve problems related to similar prot_U       P7S_UW, P7U_U         pply the acquired knowledge in the field of automatic cientific disciplines       P7S_UW, P7U_U         nake economic assessment of the proposed technical appects in utomatic control and robotics systems       P7S_UW, P7U_U         onturnatic control and robotics systems       P7S_UW, P7U_U         ontrol and robotics to solve problems related to similar prot_U       P7S_UW, P7U_U         ontrol and robotics systemic and non-technical aspects in utomatic control and robotics systems       P7S_UW, P7U_U         ontrol and robotics engineer with diverse recipients, and prot_U       P7S_UK, P7U_U

AR2_U09	use a foreign language at at least B2+ level of the European System of Language Description in the area of specialist terminology, for the free use of professional literature, as well as the preparation and presentation of presentations on the implementation of a project or research task	P7U_U
AR2_U10	manage the team's work, plan and implement lifelong learning and guide others in this area	P7S_UO, P7S_UU, P7U_U
Social com	petences: is ready to	
AR2_K01	analyze on its merits the received content and for its critical evaluation	P7S_KK, P7U_K
AR2_K02	use expert opinions and recognize the importance of knowledge in the field of technical sciences and humanities, economics and social sciences necessary in solving cognitive and practical problems	P7S KK
AR2_K03	meet social needs, undertake and coordinate initiatives for the social environment	P7S_KO, P7U_K
AR2_K04	act for the public interest	P7S_KO P7U_K
AR2_K05	think and act in an entrepreneurial way in the field of professional roles	
AR2_K06	responsibly fulfill professional duties, continuously train in issues related to the nature of professional roles	P7S_KR, P7U_K
AR2_K07	comply with the rules of professional ethics and take steps to comply with these principles by subordinate personnel	P7S_KR, P7U_K

# Study programme for full-time studies Automatic Control and Robotics

## Full-time study programme

#### Study programme: Automatic Control and Robotics

#### Master degree, general-academic profile

Semester I									
No	Module ID	Module name	Hours	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$					
No	Module ID	Module name	L	С	LC	SW	Р	Total         E0            45            75            45	ECTS
1	MYAR2S01001	Optimization methods	30			15		45	3
3	MYAR2S01002	Control theory (E)	30	30		15		75	6
4	MYAR2S01003	Real time controllers	15			30		45	4
5	MYAR2S01004	Artificial intelligence systems	30				15	45	3
6	MYAR2S01005	Signal and image processing	30	-	30			60	5
8	MYAR2S01006	Control systems for robots (E)	15	-	30			45	4
9	MYAR2S01007	Identification of control systems	30	-		15		45	3
	MYAR2S01008	Foreign language English (B2+) *							
10	MYAR2S01009	Foreign language English (C1) *		20	20			30	2
10	MYAR2S01010	Foreign language Russian *		30				30	2
	MYAR2S01011	Foreign language German *							
	Total				60	75	15	390	30

	Semester II								
No	Madula ID	Madula nama	Hours	of teachi	ng				
No Module ID		ID Module name	L	С	LC	SW	Р	Total	ECTS
1		Specialization courses: industrial process control (2E) *	150		60	150		360	30
Tota	al IPC		150	0	60	150	0	360	30
2		Specialization courses: computer systems (2E) *	150		45	135	30	360	30
Tota	al CS		150	0	45	135	30	360	30

	Semester III									
No	Module ID	Module name	Hours	of teachi	ng					
NO	Module ID	Module name	L	С	LC	SW	Р	30 2	ECTS	
1	MYAR2S03001	Implementation of control algorithms	15		15	30		60	4	
2	MYAR2S03002	Diploma seminar *				30		30	2	
3	MYAR2S03003	Innovative enterprise and technology transfer *	15	15				30	3	
	MYAR2S03004	HES II, HES III (2 of 6): World economy *								
	MYAR2S03005	Founding and financing of start-ups *						30		
1	MYAR2S03006	Market investigations *	2 x 15						2 x 1 =	
4	MYAR2S03007	Industrial marketing *	- 30	- = 30 -					2	
	MYAR2S03008	Management of project teams *								
	MYAR2S03009	Management of career *								
5	MYAR2S03010	Specialistic lecture *	30					30	2	
6	MYAR2S03011	Diploma thesis *							15	
7	MYAR2S03012	Vocational training *							2	
		Total	90	15	15	60	0	180	30	

# Specialization: industrial control

#### Semester II

Na	Madula ID	Madula nama	Hours of	of teachin	g				
No	Module ID	Module name	L	С	LC	SW	Р	Total	ECTS
1	MYAR2S12001	Interim work project *				30		30	2
2	MYAR2S12002	Networked automation systems (E) *	30		15	15		60	5
3	MYAR2S12003	Testing of control systems *	15		30			45	4
4	MYAR2S12004	Decision support in technical diagnostics *	15			15		30	2
5	MYAR2S12005	Automation and robotization systems *	45			30		75	6
6	MYAR2S12006	Nonlinear control systems (E) *	30			30		60	6
7	MYAR2S12007	Control of manufacturing processes *	15		15	30		60	5
	Total			0	60	150	0	360	30

## Specialization: informatics systems

Semester II

1	Kod	Nerve predmictu	Liczba	iczba godzin		1		Punkty	
Lp.	przedmiotu	Nazwa przedmiotu	W	C	L	Ρ	Ps	Suma	<b>ECTS</b> 2 5 5 5
1	MYAR2S22001	Interim work project *				30		30	2
2	MYAR2S22002	Ethernet industrial networks (E) *	30		15	15		60	5
3	MYAR2S22003	Artificial neural networks and expert systems (E) *	30			-	30	60	5
4	MYAR2S22004	Cooperation of robots *	15			30		45	4
5	MYAR2S22005	Intelligent technical systems *	15			30		45	4
6	MYAR2S22006	Automation systems *	30			15		45	4
7	MYAR2S22007	Autonomous systems *	30		30	15		75	6
		Total	150	0	45	135	30	360	30